

# HighPROTEC-2 | PROTECTION TECHNOLOGY MADE SIMPLE

MRM4-2 | MOTOR PROTECTION DEVICE



- DNP 3.0
- Multiple Communication with one device
- ANSI Menu structure
- · Page Editor
- New front plate with USB
- IEC61850 with LC interface

### **FUNCTIONS**

The MRM4 is a protection relay which uses the latest Dual-Core-Processor Technology to provide precise and reliable protective functions and is very easy to operate. The MRM4 provides all necessary functions to protect low and medium voltage motors at all power levels. The protection functions are based on current measurement. They supervise the motor start sequence (motor start), they detect a stall or locked rotor condition and they monitor the thermal condition of the motor. Overcurrent and earth overcurrent protection as well as unbalanced load protection is included in the protection package. The status and operation of the motor will also be monitored by means of the statistic and trend recorder. All important events and measuring values will be logged by means of the start, event, failure and disturbance recorder.

### **APPLICABLE FOR:**

→ Low and high voltage asynchronous motors. Protection based on current measurement values

# MOTOR PROTECTION **FUNCTIONS**

- → Thermal overload protection 49M
- → Locked rotor Protection 51LRS
- → JAM or Stall protection 51LR
- → Underload protection 37
- → Motor start 48
- → Starts per Hour 66
- → Negative phase sequence (current unbalance) 46
- → Overcurrent/short circuit prot. 50P/51P
- → Earth overcurrent- and short circuit protection 50N/51N
- → Reclosing lockout 86
- RTD supervision via external temperature box (Type MRM4-B, on request)

# SYSTEM SUPERVISION **FUNCTIONS**

- → CBF, circuit breaker failure 50BF
- TCS, trip circuit supervision via digital inputs 74TC
- CTS, current transformer supervision 60

## **HISTORY COUNTER**

→ Motor starts values, Numbers of alarms and trips of all important protection functions like I, IG, Thermal supervision, JAM, undercurrent and Negative phase sequence

## **TOTAL COUNTER**

- → Breaker wear values
- Motor run time
- Motor operation counter
- History

## **MOTOR START RECORDER**

- → Max. RMS values of phase currents
- Negative phase sequence currents
- Start duration
- Used thermal capacity
- Successful starts
- Temperature profile (optional)

# STATISTIC RECORDER

- Number of successful starts
- Average I2T values
- Average max. start current

# ADDITIONAL RECORDERS

- Disturbance recorder: 120 s non volatile
- Fault recorder: 20 faults
- Event recorder: 300 events
- Trend recorder: 4000 non volatile entries

# **COMMUNICATION OPTIONS**

- → IFC61850
- Profibus DP
- Modbus RTU or Modbus TCP
- IEC60870-5-103
- DNP 3.0 (RTU, TCP, UDP)

### **PC TOOLS**

- Setting and analyzing software Smart view for free
- Including page editor to design own pages



# **COMMISSIONING SUPPORT**

- → USB connection
- Customizable Display (Single-Line, ...)
- Customizable Inserts
- Copy and compare parameter sets
- → Configuration files are convertible
- → Forcing and disarming of output relays
- → Fault simulator: current and voltage
- Graphical display of tripping characteristics
- → 7 languages selectable within the relay

# LOGIC

→ Up to 80 logic equations for protection, control and monitoring

## TIME SYNCHRONISATION

→ SNTP or IRIG-B00X

# **ADDITIONAL HIGHLIGHTS**

- 20 mA output (Type MRM4-B)
- Long starting time for reduced voltage starts
- **Emergency Start**
- Incomplete sequence
- Anti-backspin time delay
- Permitted number of cold starts
- Supervision of starts per hour
- → Mechanical load shedding
- → Zero speed detection (stall) via digital input
- Motor stop inputs
- External alarm and trip inputs
- Multiple setting groups

# **FUNCTIONAL OVERVIEW**

	Elements	ANSI
Protective Functions		
IB, thermal overload protection		49M
I, time overcurrent and short circuit protection (non direction) (instantaneous, definite time, characteristicsaccording to IEC60255, ANSI	6	50P, 51P
12, unbalanced load protection with evaluation of the negative phase sequence current	2	46
IG, earth time overcurrent and short circuit protection (non direction) (instantaneous, definite time, characteristics according to IEC60255, ANSI	4	50N, 51N
I< underload protection	2	37
Reclosing lockout		49R
Incomplete sequence		
JAM protection		51LR
Locked rotor Protection		51LRS
Motor start		48
Starts per Hour		66
Start control input		
Reversing mode		
Emergency start		

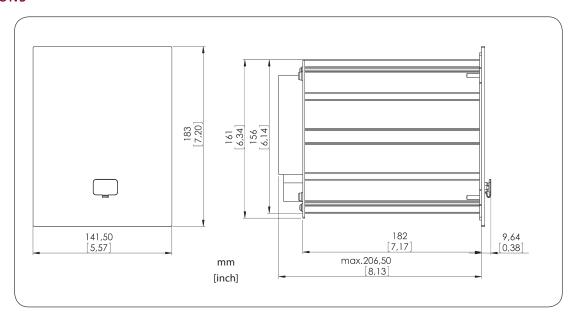
# **Control and Logic**

Control: Position indication, supervision time management and interlockings for 1 breaker

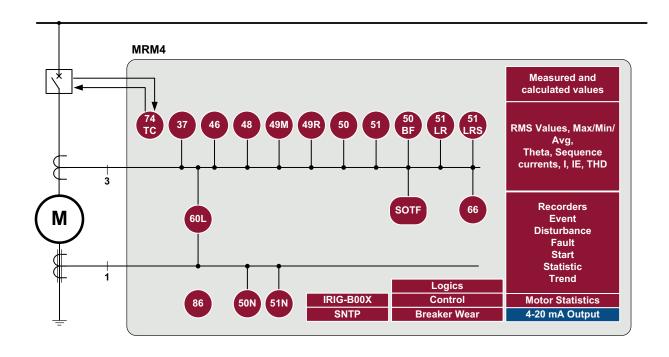
Logic: Up to 80 logic equations, each with 4 inputs, selectable logical gates, timers and memory function

Supervision Functions		
CBF, circuit breaker failure	1	50BF/62BF
TCS, trip circuit supervision via digital inputs	1	74TC
CTS, current transformer supervision	1	60L
Demand management and peak value supervision (current)		
Breaker wear with programmable wear curves		
Recorders: Disturbance Recorder, Fault recorder, Event recorder, Trend recorder, Motor Start recorder, Statistic recorder		

# **DIMENSIONS**



# **FUNCTIONAL OVERVIEW IN ANSI FORM**



## **APPROVALS**





certified regarding UL508 (Industrial Controls)



certified regarding CSA-C22.2 No. 14 (Industrial Controls)

Type tested according to IEC60255-1

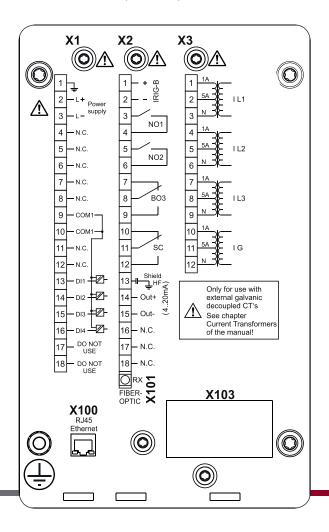


certified by EAC (Eurasian Conformity)

complies with IEEE 1547-2003 amended by IEEE 1547a-2014

complies with ANSI C37.90-2005

# **CONNECTIONS** (EXAMPLE)



## **ORDER FORM MRM4-2**

Version 2 v	with USB, enhance	ed communication	and user opt	ions					
Digital Inputs	Binary output relays	Analog Inputs/ Outputs	Housing	Large display					
8	6	0/0	B1	-		Α			
4	4	0/1	B1	_		В			
Hardware	variant 2								
Phase Curr	rent 5 A/1 A, Grou	ınd Current 5 A/1 A	4			0			
Phase Curr	ent 5 A/1 A, Sensi	tive Ground Curren	it 5 A/1 A			1			
Housing a	and mounting								
Door moui	nting						Α		
Door mou	nting 19" (flush m	ounting)					В		
Communi	cation protocol								
Without pr								Α	
		3, DNP3.0 RTU   <i>RS</i> 4						B <b>*</b>	
Modbus TO	CP, DNP3.0 TCP/U[	DP   Ethernet 100 ME	8/RJ45					C*	
	P   optic fiber/ST-co	onnector						D*	
Profibus-D	P   RS485/D-SUB							E*	
	•	3, DNP3.0 RTU   <i>opi</i>		nnector				F*	
Modbus RTU, IEC60870-5-103, DNP3.0 RTU   <i>RS485/D-SUB</i>						G*			
IEC61850, I	Modbus TCP, DNP	3.0 TCP/UDP   Ether	net 100MB/RJ	45				H*	
		u, DNP3.0 RTU   <i>RS</i>						*	
		DP   Ethernet 100 Mi							
IEC61850, Modbus TCP, DNP3.0 TCP/UDP   Optical Ethernet 100MB/LC duplex connector						K*			
		DP   Optical Ethernet	: 100MB/LC du	iplex connector				L*	
Harsh Env	rironment Optio	n							
None									А
Conformal	Coating								В

\* Within every communication option only one communication protocol is usable. Smart view can be used in parallel via the Ethernet interface (RJ45).

Weight (max. components)

The parameterizing- and disturbance analyzing software Smart view is included in the delivery of HighPROTEC devices.

**Current inputs** 4 (1 A and 5 A) with automatic CT Disconnect Switching thresholds adjustable via software Digital inputs Power supply Wide range power supply  $24\,V_{_{DC}}$  -  $270\,V_{_{DC}}$  /  $48\,V_{_{AC}}$  -  $230\,V_{_{AC}}$  (-20/+10%) **Terminals** All terminals plug type Type of enclosure (Front) IP54 Dimensions of housing 19" flush mounting: 141.5 mm x 173 mm x 209 mm  $(W \times H \times D)$ 5.571 in. x 6.811 in. x 8.228 in. Door mounting: 141.5 mm x 183 mm x 209 mm 5.571 in. x 7.205 in. x 8.228 in.

approx. 2.9 kg / 6.393 lb

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